Mean Field Equilibria of Dynamic Auctions

Ramesh Johari

Stanford University

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A motivating example: dynamic auctions with learning
A mean field model
Mean field equilibrium
Characterizing MFE
Using MFE: dynamic revenue equivalence, reserve prices
Other models: budget constraints, unit demand bidders
Open problems
PART I: A MOTIVATING EXAMPLE
Sponsored search markets
Sponsored search markets

Advertisers bid on various keywords to get their ads placed on the search page.

On each query, an auction occurs among the relevant advertisers, and winners get their ads placed.

**Cost-per-click (CPC):** The good being auctioned is a click, i.e., advertisers pay only if a user clicks on their ad.

Advertisers care for **conversion** – how an ad click converts into sales or profit.
Sponsored search markets

There is a **mismatch** between the good being auctioned and what the advertisers value.

This creates a **dynamic incentive**: Bidders must simultaneously **estimate** their conversion rates while bidding on keywords.
Repeated auctions with learning

Here we consider a simple abstraction:

- $N$ bidders
- Bidder $i$ has a valuation $v_i \in [0, 1]$ that is *unknown* to her
  - Think of this as the conversion rate.
- $v_i$ distributed according to prior $F_i$
  (independent across bidders)
- Bidders compete in a sequence of second price auctions
What should a bidder do?

First suppose there is a single period.

*Dominant strategy:* bid expected value (according to current belief).
What should a bidder do?

What about multiple periods?

There is now a **value for learning**:

Agents will tend to *overbid* above expected valuation, because learning about their value might help them in future periods
What should a bidder do?

But the amount to overbid depends critically on what a bidder believes about her competitors.

The classical solution concept is perfect Bayesian equilibrium (PBE): A bidder optimizes with respect to:

- her beliefs over all that is unknown, given the history so far; and
- her prediction of how others will behave in the future, in response to her action today.
Challenge 1: PBE is implausible

There seems to be a “law of large numbers of rationality”:

Complex beliefs and forecasting become uncommon even with relatively small numbers of players (5-10).

Therefore PBE seems to be a highly implausible model of agent behavior, even in settings with fairly sophisticated agents.
Challenge 2: PBE is intractable

The dynamic optimization problem of an agent has a very high dimensional state space:

An agent optimizes given beliefs over all that is unknown.

Even computing best responses is prohibitive, let alone equilibria!
This is a bad place to be:

One does not want theory to be both intractable and implausible.

As a result, we leave engineers with few tools to guide design:

How does market structure, auction format, reserve prices, etc. affect bidder behavior?
PART II: A MEAN FIELD MODEL
“Bounded rationality” models offer a way out of the impasse; but which bounded rationality approach to use?

We’ll discuss an approximation founded on the premise that there are a large number of bidders present.

This is called a **mean field model**.
A formal model

We now formally describe a mean field model for dynamic auctions with learning.

Key components:

- Bidder model: learning and payoffs
- The “mean field”: competitors’ bid distribution
A formal model

A bidder participates in a sequence of second price auctions.

\( \alpha \) bidders in each auction.

The bidder lives for a geometric(\( \beta \)) lifetime (mean \( 1/(1 - \beta) \)).

The bidder has an **unknown** private valuation \( v \in [0, 1] \):

\[
P(reward_t = 1) = 1 - P(reward_t = 0) = v
\]
Learning model

Initial prior: \( \text{Beta}(m, n) \)

- \((m, n)\) and \(\nu\) chosen on arrival.

Mean: \( \mu(m, n) = \frac{m}{m + n} \)

Variance: \( \sigma^2(m, n) \) decreasing in \(m\) and \(n\)

Belief update is through Bayes’ rule;
let \(s_k = (m_k, n_k)\) denote belief parameters after \(k'\)th auction.
Belief update

On losing the auction:

\[ \text{Density of prior} \xrightarrow{\text{Beta}(m, n)} \text{Density of posterior} \]

\[ \text{Valuation} \]

\[ \text{Beta}(m, n) \]

\[ \text{Valuation} \]

\[ \text{Beta}(m, n) \]
On winning the auction, and getting a positive reward:

\[ \text{Beta}(m, n) \xrightarrow{\text{Density of prior}} \text{Beta}(m + 1, n) \]
On winning the auction, and getting zero reward:

\[ \text{Beta}(m, n) \rightarrow \text{Beta}(m, n + 1) \]
Maximize the total expected payoff over the lifetime

(Per period payoff = reward - payment)
The “mean field” market

Suppose the *distribution* of bids in the market is \( g \)

The **mean field** assumption:

For a fixed agent, in each of her auctions, bids of the other \( \alpha - 1 \) agents are sampled i.i.d. from \( g \).
Why is the mean field model reasonable?

In sponsored search, advertisers use *bid landscape* information to model the rest of the market. Bid landscapes use the last week’s data to give aggregated estimates of cost-per-click, number of clicks, and number of impressions that can be expected for a given bid.

The mean field model captures this information structure.
Simulation based on performance from Feb 2, 2012 to Feb 8, 2012

These estimates do not guarantee similar results in the future. Learn more

<table>
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<tr>
<th>Max. CPC</th>
<th>Estimated Impr.</th>
<th>Estimated Top Impr.</th>
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<tr>
<td>$5.67</td>
<td>17,000</td>
<td>53</td>
</tr>
<tr>
<td>$3.40</td>
<td>14,500</td>
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<td>3</td>
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<tr>
<td>$1.45</td>
<td>4,530</td>
<td>--</td>
</tr>
<tr>
<td>$1.00</td>
<td>2,040</td>
<td>--</td>
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</tbody>
</table>

Use a different bid: $
Questions

- What is a reasonable notion of equilibrium for this system?
- Does it exist?
- What is the structure of bidders’ optimal strategy?
- Do mean field models approximate games with finitely many players?
- How do we compute an equilibrium?
PART III: MEAN FIELD EQUILIBRIUM
Mean field equilibrium

Inspired by large markets.

In an MFE:

Agents do not track individual competitors.

Each agent plays against a “stationary” market.
Mean field equilibrium

Optimality:
- Stationary market
- Actions are optimal

Consistency:
- Given agents’ actions
- Same stationary distribution
A bid distribution $g$ and a strategy $C$ constitute an MFE if

**Optimality:**
- Fixed bid distribution $g$
- Strategy $C$ is optimal

**Consistency:**
- Given each agent follows $C$
- Market bid distribution is $g$
Mean field equilibrium: Formal definition

Fix a bid distribution \( g \).

- Let \( C(\cdot|g) \) be an optimal strategy for the agent’s expected lifetime profit maximization problem, given \( g \).
- Let \( \Phi \) be the steady state distribution (on valuations and states) induced by the resulting agent dynamics under the strategy \( C(\cdot|g) \), and assuming other agents’ bids are drawn from \( g \). (Note that these dynamics include regeneration.)
- Let \( g' \) be the new steady state bid distribution derived by integrating the strategy \( C(\cdot|g) \) against the steady state distribution \( \Phi \).

The bid distribution \( g \) is a MFE bid distribution if it is a fixed point of this map.
Mean field models arise in a wide variety of fields: physics, applied math, engineering, economics, ...

Extensive work on mean field models for static games (e.g., competitive equilibrium, nonatomic games, etc.)
Mean field equilibrium: Related work

Mean field models in dynamic games:

- **Economics:** Jovanovic and Rosenthal (1988); Stokey, Lucas, Prescott (1989); Hopenhayn (1992); Sleet (2002); Weintraub, Benkard, Van Roy (2008, 2010); Acemoglu and Jepsen (2010); Bodoh-Creed (2011)

- **Control:** Glynn, Holliday, Goldsmith (2004); Lasry and Lions (2007); Huang, Caines, Malhamé (2007-2012); Gueant (2009); Tembine, Altman, El Azouzi, le Boudec (2009); Yin, Mehta, Meyn, Shanbhag (2009); Adlakha, Johari, Weintraub (2009, 2011)

- **Finance:** Duffie, Malamud, Manso (2009, 2010)

- **Dynamic auctions:** Wolinsky (1988); McAfee (1993); Backus and Lewis (2010); Iyer, Johari, Sundararajan (2011); Gummadi, Proutièrè, Key (2012); Bodoh-Creed (2012)

(Other names for MFE: Stationary equilibrium, oblivious equilibrium)
Another relevant line of literature is on *dynamic mechanism design*.

*Examples:* Athey and Segal (2007); Bergemann and Valimaki (2010); etc.

- In dynamic mechanism design, a *hard* optimization problem is solved (optimal dynamic allocation), and payments are structured so equilibrium behavior bidder is *simple* (truth telling).

- But, in many real markets: repetitions of *simple* mechanisms are implemented, leading to *complex* equilibrium bidder behavior.
PART IV: CHARACTERIZING MFE
Characterizing MFE

- Optimal strategies
- Existence of MFE
- Approximation and finite games
- Computation
PART IV-A: Optimal strategies
Suppose the distribution of bids in the market is $g$

Probability of winning: \[ q(b|g) = g(b)^{\alpha-1} \]

Expected payment: \[ p(b|g) \]
Let $V(s|g)$ denote the agent’s maximum possible expected lifetime payoff, when her current belief is $s$, and the population bid distribution is $g$.

By the principle of optimality for discounted dynamic programming, $V$ must satisfy Bellman’s equation.
Given $g$, agent’s value function satisfies Bellman’s equation:

$$V(s|g) = \max_{b \geq 0} \left\{ q(b|g)\mu(s) - p(b|g) + \beta q(b|g)\mu(s)V(s + e_1|g) \right.$$

$$+ \beta q(b|g)(1 - \mu(s))V(s + e_2|g) + \beta (1 - q(b|g))V(s|g) \right\}$$
MFE: Agent’s decision problem

Given $g$, agent’s value function satisfies Bellman’s equation:

$$V(s|g) = \max_{b \geq 0} \left\{ q(b|g)\mu(s) - p(b|g) + \beta q(b|g)\mu(s)V(s + e_1|g) + \beta q(b|g)(1 - \mu(s))V(s + e_2|g) + \beta(1 - q(b|g))V(s|g) \right\}$$

(1) Expected payoff in current auction
Given $g$, agent’s value function satisfies Bellman’s equation:

$$V(s|g) = \max_{b \geq 0} \left\{ q(b|g)\mu(s) - p(b|g) + \beta q(b|g)\mu(s) V(s + e_1|g) \right. \right.$$ 

$$\left. + \beta q(b|g)(1 - \mu(s))V(s + e_2|g) + \beta(1 - q(b|g))V(s|g) \right\}$$

(2) Future expected payoff on winning and positive reward:
Given $g$, agent’s value function satisfies Bellman’s equation:

$$V(s|g) = \max_{b \geq 0} \left\{ q(b|g)\mu(s) - p(b|g) + \beta q(b|g)\mu(s)V(s + e_1|g) \\
+ \beta q(b|g)(1 - \mu(s))V(s + e_2|g) + \beta(1 - q(b|g))V(s|g) \right\}$$

(3) Future expected payoff on winning and **zero** reward:
Given $g$, agent’s value function satisfies Bellman’s equation:

$$V(s|g) = \max_{b \geq 0} \left\{ q(b|g)\mu(s) - p(b|g) + \beta q(b|g)\mu(s)V(s + e_1|g) \\
+ \beta q(b|g)(1 - \mu(s))V(s + e_2|g) + \beta(1 - q(b|g))V(s|g) \right\}$$

(4) Future expected payoff on losing:
Given $g$, agent’s value function satisfies Bellman’s equation:

$$V(s|g) = \max_{b \geq 0} \left\{ q(b|g)\mu(s) - p(b|g) + \beta q(b|g)\mu(s)V(s + e_1|g) \right. \\
\left. \quad + \beta q(b|g)(1 - \mu(s))V(s + e_2|g) + \beta(1 - q(b|g))V(s|g) \right\}$$
MFE: Agent’s decision problem

Given $g$, agent’s value function satisfies Bellman’s equation:

$$V(s|g) = \max_{b \geq 0} \left\{ q(b|g)\mu(s) - p(b|g) + \beta q(b|g)\mu(s)V(s + e_1|g) \right.$$  
$$+ \beta q(b|g)(1 - \mu(s))V(s + e_2|g) + \beta (1 - q(b|g))V(s|g) \right\}$$
Rewriting:

\[ V(s|g) = \max_{b \geq 0} \left\{ q(b|g)C(s|g) - p(b|g) \right\} + \beta V(s|g), \]

where

\[
C(s|g) = \mu(s) + \beta \mu(s)V(s + e_1|g) \\
+ \beta (1 - \mu(s))V(s + e_2|g) - \beta V(s|g).
\]
Agent’s decision problem is

$$\max_{b \geq 0} \left\{ q(b|g)C(s|g) - p(b|g) \right\}$$
Agent’s decision problem is

\[
\max_{b \geq 0} \left\{ q(b|g)C(s|g) - p(b|g) \right\}
\]

Same decision problem as in

- **Static** second-price auction
- against \(\alpha - 1\) bidders drawn i.i.d. from \(g\)
- with agent’s **known** valuation \(C(s|g)\).
Agent’s decision problem is

$$\max_{b \geq 0} \left\{ q(b|g)C(s|g) - p(b|g) \right\}$$

Same decision problem as in

- **Static** second-price auction
- against $\alpha - 1$ bidders drawn i.i.d. from $g$
- with agent’s **known** valuation $C(s|g)$.

We show $C(s|g) \geq 0$ for all $s$

$\implies$ Bidding $C(s|g)$ at posterior $s$ is **optimal**!
Conjoint valuation

\[ C(s|g) : \textbf{Conjoint valuation} \text{ at posterior } s \]

\[ C(s|g) = \mu(s) + \beta\mu(s)V(s + e_1|g) + \beta(1 - \mu(s))V(s + e_2|g) - \beta V(s|g) \]
Conjoint valuation

\[ C(s|g) : \textbf{Conjoint valuation} \text{ at posterior } s \]

\[ C(s|g) = \mu(s) + \beta \mu(s) V(s + e_1|g) + \beta (1 - \mu(s)) V(s + e_2|g) - \beta V(s|g) \]

\textbf{Conjoint valuation} = \textbf{Mean} + \textbf{Overbid}

(We show Overbid \geq 0)
Conjoint valuation: Overbid

Overbid: $\beta \mu(s) V(s + e_1 | g) + \beta (1 - \mu(s)) V(s + e_2 | g) - \beta V(s | g)$
Conjoint valuation: Overbid

Overbid: \( \beta \mu(s)V(s + e_1|g) + \beta(1 - \mu(s))V(s + e_2|g) - \beta V(s|g) \)

Expected marginal future gain from one additional observation about private valuation
Conjoint valuation: Overbid

Overbid: $\beta \mu(s) V(s + e_1 | g) + \beta (1 - \mu(s)) V(s + e_2 | g) - \beta V(s | g)$

Overbid

Expected marginal future gain from **one additional observation** about private valuation

**Simple description of agent behavior!**
PART IV-B: Existence of MFE
Existence of MFE

We make one assumption for existence:

*We assume that the distribution from which the value and belief of a single agent are initially drawn has compact support with no atoms.*
Existence of MFE

**Theorem**

*A mean field equilibrium exists where each agent bids her conjoint valuation given her posterior.*

- Show: With the right topologies, $F$ is continuous
- Show: Image of $F$ is compact (using previous assumption)
PART IV-C: Approximation and MFE
Approximation

Does an MFE capture rational agent behavior in finite market?

Issues:

■ Repeated interactions $\implies$ agents no longer independent.
■ Keeping track of history will be beneficial.

Hope for approximation only in the asymptotic regime
Approximation

Theorem

As the number of agents in the market **increases**, the maximum additional payoff on a **unilateral** deviation converges to zero.

As the market size increases,

\[
\text{Expected payoff under } \text{optimal strategy}, \text{ given others play } C(\cdot|g) \quad \rightarrow \quad 0
\]
Approximation

Look at the market as an interacting particle system.

**Interaction set** of an agent: all agents influenced by or that had an influence on the given agent (from Graham and Méléard, 1994).

**Propagation of chaos**  $\Rightarrow$ As market size increases, any two agents’ interaction sets become disjoint with high probability.
Theorem

As the number of agents in the market increases, the maximum additional payoff on a unilateral deviation converges to zero.

Mean field equilibrium is good approximation to agent behavior in finite large market.
PART IV-D: Computing MFE
A natural algorithm inspired by model predictive control (or certainty equivalent control)

Closely models market evolution when agents optimize given current average estimates
MFE computation

Initialize the market at bid distribution $g_0$.

- Compute conjoint valuation
- Evolve the market one time period
- Compute new bid distribution

Continue until successive iterates of bid distribution are sufficiently close.

- Stopping criterion: total variation distance is below tolerance $\epsilon$. 
Algorithm converges within 30-50 iterations in practice, for reasonable error bounds ($\epsilon \sim 0.005$)

Computation takes $\sim 30-45$ mins on a laptop.
Overbidding

Evolution of bid

Bid and mean

Number of auctions

Actual bid

Current mean
Discussion

In the dynamic auction setting, proving convergence of this algorithm remains an open problem.

However, we have proven convergence of similar algorithms in two other settings:

- Dynamic supermodular games (Adlakha and Johari, 2011)
- Multiarmed bandit games (Gummadi, Johari, and Yu, 2012)

Alternate approach: Best response dynamics (Weintraub, Benkard, Van Roy, 2008)
PART V: USING MFE IN MARKET DESIGN
Auction format

The choice of auction format is an important decision for the auctioneer.

We consider markets with repetitions of a standard auction:

1. Winner has the highest bid.
2. Zero bid implies zero payment.

Example: First price, second price, all pay, etc.
Repeated standard auctions

Added complexity due to strategic behavior:

For example, the static first-price auction naturally induces **underbidding**.

This is in conflict with overbidding due to learning.
Repeated standard auctions

Added complexity due to strategic behavior:

For example, the static first-price auction naturally induces underbidding.

This is in conflict with overbidding due to learning.

We show a dynamic revenue equivalence theorem:

\[
\text{Maximum revenue over all MFE of repeated second-price auction.} = \text{Maximum revenue over all MFE of any repeated standard auction.}
\]
Added complexity due to strategic behavior:

For example, the static first-price auction naturally induces **underbidding**.

This is in conflict with overbidding due to learning.

We show a **dynamic revenue equivalence** theorem:

Maximum revenue over all MFE of repeated **second-price** auction.  

=  

Maximum revenue over all MFE of any repeated **standard** auction.

All standard auction formats yield the **same** revenue!
Dynamic revenue equivalence

Maximum revenue over all MFE of repeated second-price auction. =

Maximum revenue over all MFE of any repeated standard auction.

Proof in two steps:
1 $\leq$: Composition of conjoint valuation and static auction behavior.
2 $\geq$: technically challenging (constructive proof).
Reserve price

Setting a reserve price can increase auctioneer’s revenue.

Effects of a reserve:

1. Relinquishes revenue from agents with low valuation
2. Extracts more revenue from those with high valuation
Setting a reserve price can increase auctioneer’s revenue.

Effects of a reserve:

1. Relinquishes revenue from agents with low valuation
2. Extracts more revenue from those with high valuation
3. Imposes a learning cost:
   - Precludes agents from learning, and reduces incentives to learn
Reserve price

Consider repeated second price auction setting.

Due to learning cost, agents change behavior on setting a reserve.

Auctioneer sets a reserve $r$ and agents behave as in an MFE with reserve $r$.

Defines a game between the auctioneer and the agents.
Optimal reserve

Two approaches:

1. **Nash**: Ignores learning cost.
   
   Auctioneer sets a reserve \( r \) assuming bid distribution is fixed, and agents behave as in a corresponding MFE.

2. **Stackelberg**: Includes learning cost.
   
   Auctioneer computes revenue in MFE for each \( r \), and sets the maximizer \( r_{OPT} \).

We compare these two approaches using numerical computation.
By definition, $\Pi(r_{OPT}) \geq \Pi(r_{NASH})$.

$\Pi(r_{OPT}) - \Pi(0)$ is greater than $\Pi(r_{NASH}) - \Pi(0)$ by $\sim 15 - 30\%$.

- Improvement depends on the distribution of initial beliefs of arriving agents.

By ignoring learning, auctioneer may incur a potentially significant cost.
There is a significant point to be made here:

These types of comparative analyses are very difficult (if not impossible) using classical equilibrium concepts:

If equilibrium analysis is intractable, then we can’t study how the dynamic market changes as we vary parameters.
PART VI: OTHER DYNAMIC INCENTIVES
PART VI-A: Budget constraints
Now suppose that a bidder faces a budget constraint $B$, but knows her valuation $v$.

The remainder of the specification remains as before.

In particular, the agent has a geometric($\beta$) lifetime, and assumes that her competitors in each auction are i.i.d. draws from $g$. 
Then a bidder’s dynamic optimization problem has the following value function:

\[
V(B, v|g) = \max_{b \leq v} \left\{ q(b|g)v - p(b|g) + \beta(1 - q(b|g))V(B, v|g) \\
+ \beta q(b|g)\mathbb{E}[V(B - b_-, v|g)|b_- \leq b] \right\},
\]

where \(b_-\) is the highest bid among the competitors.
Some rearranging gives:

\[ V(B, v|g) = \frac{1}{1 - \beta} \max_{b \leq v} \left\{ q(b|g)v - p(b|g) + \beta q(b|g) \mathbb{E} [V(B, v|g) - V(B - b\_, v|g)|b\_ \leq b] \right\}, \]

where \( b\_ \) is the highest bid among the competitors.
Suppose that $B$ is very large relative to $v$. Then we can approximate:

$$V(B, v|g) - V(B - b_-, v|g)$$

by:

$$V'(B, v|g)b_-. $$
Since:

$$q(b|g)E[b_-|b_- \leq b] = p(b|g),$$

conclude that:

$$\beta q(b|g)E[V(B, v|g) - V(B - b_-, v|g)|b_- \leq b] \approx \beta V'(B, v|g)p(b|g).$$
Decision problem: large $B$

Substituting we find:

$$V(B, v|g) = \frac{1 + \beta V'(B, v|g)}{1 - \beta} \max_{b \leq v} \left\{ q(b|g) \left( \frac{v}{1 + \beta V'(B, v|g)} \right) - p(b|g) \right\}.$$ 

As before: this is the same decision problem as an agent in a static second price auction, with “effective” valuation $v/(1 + \beta V'(B, v|g))$. 
Moral:

In a mean field model of repeated second price auctions with budget constraints (and with $B \gg \nu$), an agent’s optimal bid is:

$$\nu \frac{1}{1 + \beta V'(B|g)}.$$

Note that agents **shade** their bids:

This is due to the opportunity cost of spending budget now.
This model can be formally studied in a limit that captures the regime where $B$ becomes large relative to the valuation.

See Gummadi, Proutière, Key (2012) for details.
PART VI-B: Unit demand bidders
Now consider a setting where a bidder only wants one copy of the good, and her valuation is $v$.

She competes in auctions until she gets one copy of the good; discount factor for future auctions $= \delta$.

The remainder of the specification remains as before.

In particular, the agent has a geometric($\beta$) lifetime, and assumes that her competitors in each auction are i.i.d. draws from $g$. 
Then a bidder’s dynamic optimization problem has the following value function:

\[
V(v|g) = \max_{b \leq v} \{q(b|g)v - p(b|g) + \beta(1 - q(b|g))\delta V(v|g)\}.
\]
Rearranging:

\[ V(v|g) = \frac{1}{1 - \beta} \max_{b \leq v} \{ q(b|g)(v - \beta \delta V(v|g)) - p(b|g) \}. \]

As before: this is the same decision problem as an agent in a static second price auction, with “effective” valuation \( v - \beta \delta V(v|g) \).
Moral:

In a mean field model of repeated second price auctions with unit demand bidders, an agent’s optimal bid is:

\[ v - \beta \delta V(v|g). \]

Note that agents **shade** their bids:

This is due to the possibility of waiting until later to get the item.
This model has been analyzed in a much more complex setting, with many sellers and buyers, and with endogenous entry and exit.

See Bodoh-Creed (2012) for details.
PART VII: OPEN PROBLEMS
A similar analysis can be carried out for general anonymous dynamic games.

Extensions to:

- Nonstationary models (Weintraub et al.);
- Unbounded state spaces (Adlakha et al.);
- Continuous time (Tembine et al., Huang et al., Lasry and Lions, etc.).
There is an extensive literature in economics studying convergence of **large static double auctions** to:

- competitive equilibrium (with private values); or
- rational expectations equilibrium (with common values).

Analogously, which sequential auction mechanisms converge to dynamic competitive or rational expectations equilibria in large markets?

[ **Note:** dynamic incentives such as learning or budget constraints cause an efficiency loss. ]
What does it mean to say MFE is simpler than classical equilibrium concepts?

Typical argument: curse of dimensionality.

But in the end, all concepts rely on fixed point arguments to establish existence.

Can we establish in a computational complexity-theoretic framework, that MFE is simpler?
In most settings, MFE existence remains nonconstructive.

As discussed above, in some cases algorithms exist to compute MFE.

What are some other reasonable algorithms to compute MFE? In what settings can we establish uniqueness, convergence, etc.?
Interchanging limits

Our approximation theorem only holds over finite time intervals.

In general, interchanging time and number of agents is not straightforward: requires uniform convergence to mean field limit over time.

Under what conditions is this guaranteed? (See also: Glynn, 2004; Gummadi, Johari, Yu, 2012.)
MFE is valid with full **temporal mixing**: Interact with a small number of agents each period, but resample i.i.d. every time period

But MFE is also valid with **full spatial mixing**: Interact with everyone at every time period

What about more complex interaction models (e.g., random graphs that evolve over time)?
CONCLUSION
Modern large scale markets are highly dynamic, and present significant design challenges to engineers.

Approximation methods like MFE are both more tractable and more plausible than classical equilibrium approaches to such complex dynamic games.